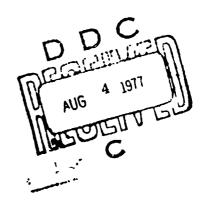


COLLECTION OF COMMERCIAL AIRCRAFT CHARACTERISTICS FOR STUDY OF RUNWAY ROUGHNESS

Anthony G. Gerardi



Final Report May 1977



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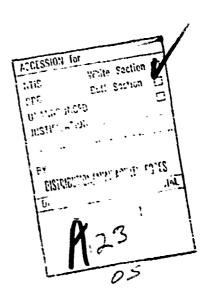
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LIST OF SYMBOLS

Symbol	Definition	<u>Unit</u>
A	Distance from rear main landing gear to aircraft CG	-,
a ₁ ,a ₂ ,a ₃ ,a ₄	Coefficients calculated to fit a polynomial curve to a runway segment	Ní
A _h	Hydraulic piston area	i n ²
A _o	Effective orifice area	i n ²
В	Distance from nose landing gear to aircraft CG	in
С	Distance from front main landing gear to aircraft CC	in
С	Damping coefficient	1/sec
c _d	Orifice coefficient	ND
FA	Pneumatic strut force	lbs
FAD	Total airplane aerodynamic drag	lbs
F _D ,F _N	Landing Gear Drag and Normal Forces .	lbs
F _F	Friction force	lbs
F _{Fn}	Strut seal friction	lbs
Fh	Hydraulic strut force	lbs
F _{s1} ,F _{s2} ,F _{s3}	Total landing gear strut forces	lbs
F _t ,F _{t1} ,F _{t2} ,F _{t3}	Landing gear tire forces	lbs
F _T	Total airplane thrust	lbs
F _{TD}	Main landing gear tire drag force	lbs
F _u ,F _L	Strut bearing friction forces, upper and lower	ibs
9	Gravitational acceleration constant	in/sec ²
I уу	Total airplane pitching inertia	lbs/in sec
•.	linear tire corina constant	lbs/in

Symbol .	Definition	Unit
L	Total airplane lift	lbs
11, 12, 13	W _{1/g} , W _{2/g} , W _{3/g}	sligs
M _{cg}	Airplane mass	sligs
Mi	The generalized mass for the ith mode	lbs-sec ² /in
P	Fully extended strut air pressure	lb/in ²
ч	Defrection due to bending	in
t ₅	rray of nondimensional time dependent coordinates which weigh the amount of motion due to the ith mode in the total motion of the aircraft	NŌ
q;	Time demivative of q	1/sec
ä ₁	Time derivative of q _i	1/sec ²
S	Strut displacement	in
· s	Time derivative of S	in/sec
;	Second time derivative of \$	in/sec ²
Δt	Taylor series sample solution time step size	sec
τ _D	Tire deflection	in
V	Fully extended strut volume	in ³
W	Total airplane weight	lbs
w_1, w_2, w_3	Unsprung landing gear weights	lbs
x	Coordinate for sample Taylor series solution	in
×	Time derivative of x	in/sec
x	Time derivative of \dot{x}	in/sec ²
x	Horizontal translation of the aircraft down the runway	ft
x	Time derivative of X	ft/sec
Ÿ	Time derivative of X	ft/sec ²
Z	Vertical displacement of the vehicle CG	in
ż	Time derivative of Z	in/sec

Symbol	Definition	<u>Unit</u>
ï Z	Time derivative of Z	in/sec ²
z ₁ ,z ₂ ,z ₃	Vertical displacement of the unsprung mass of gear number 1, 2 and 3	in
ż ₁ ,ż ₂ ,ż ₃	Time derivative of Z ₁ ,Z ₂ ,Z ₃	in/sec
z ₁ ,z ₂ ,z ₃	Time derivative of Z ₁ ,Z ₂ ,Z ₃	in/sec ²
٤١	Distance from main gear axle to the waterline of the aircraft $\text{CG}_{\ensuremath{\mathbb{C}}}$	in
ξ ₁₁ ,ξ ₁₂ ,ξ ₁₃	Modal deflection of the ith mode at gear 1, 2 and 3	in
θ	Aircraft pitch angle	rad
ė	Time derivative of θ	rad/sec
ë	Time derivative of $\dot{\theta}$	rad/sec ²
ρ _h	Hydraulic fluid density	sligs/in ³
ζį	Percent of critical damping factor for the ith mode	ND
μ_{L} μ_{U}	Sliding coefficients of friction for strut lower and upper bearings	ND
$\omega_{\mathbf{i}}$	Natural frequency of the ith mode	rad/sec

SECTION I

INTRODUCTION

Very early aircraft operated from grass airfields or graded and untreated runways. However, with the development of more sophisticated aircraft requiring higher and higher ground speeds, runway surfacing became of increasing concern. Today's modern aircraft require a pavement system structurally capable of supporting gross loads approaching a million pounds. In addition, the pavement surface must provide adequate skid resistance and must be of sufficient smoothness to prevent undue loss of fatigue life in the aircraft. The response of aircraft to the pavement irregularities has become of increasing concern in recent years. A great deal of emphasis has been placed upon the comfort and safety of aircraft ground operations and other factors related to the interaction between the pavement and the aircraft.

Because the runway and the aircraft form a coupled system with the pavement profile providing a displacement input that can radically affect the behavior of the vehicle, there is an urgent need for a means to measure pavement roughness. The Federal Aviation Administration has long been aware of this need, and in 1973 initiated research and development efforts to quantify pavement roughness. This effort began with the study of a means for rapidly collecting the runway profile. As a result of that effort, a profiling system using a laser beam as a horizontal reference datum was developed (Reference 1).

The next step was to establish roughness criteria. Considerable effort had been expended in this area, most of it dealing with the subjective rating of ride quality. However, ride quality did not deal directly with the pavement, which was the factor causing unacceptable aircraft response. Therefore, in its efforts to define runway roughness, a statistical approach to the runway profile itself was taken (Reference 2). This approach dealt with the root means square of the deviation of the profile about a normalized line. From this comes criteria for evaluating a runway profile as being acceptable as long as the RMS level is below 0.32 inches. Marginal conditions are equated to RMS levels of 0.32 to 0.36 inches and any runway having a RMS level of greater than 0.36 inches is considered to be unduly rough.

As a check of this criteria and as a means of evaluating the simulated repair of a runway having undesirable roughness, an existing taxicode developed for the US Air Force was modified to provide a way for calculating the dynamic response of commercial aircraft to runway irregularities. The modification of that computer code is the subject of this report. The use of this computer program is not to compare ride

quality between various classes of aircraft but rather to be used by the operating airlines and airport owners and operators as a means of identifying rough pavement areas and to help insure the timely maintenance of pavements in order to prevent the development of undue roughness.

Details of the development of the computer code modified in this report is provided in Reference 3. The development of the computer code is only briefly summarized in this report. In order to make the computer code useful to all commercial aircraft, these aircraft were divided into five classes based on gross weight as shown below:

Aircraft Classes

Class	Weight Group
Class A Aircraft	Less than 150,000 pounds
Class B Aircraft	150,000 - 300,000 pounds
Class & Aircraft	300,000 - 450,000 pounds
Class D Aircraft	450,000 - 600,000 pounds
Class E Aircraft	Greater than 600,000 pounds

SECTION II

MATHEMATICAL MODEL

The general airplane/runway mathematical model used for this study was the basic mathematical model developed in Reference 1. A detailed description of the components that make up this general model, as well as the assumptions made are shown in Reference 1. This report presents, in summary form, the landing gear strut and tire representation, the airplane rigid body and flexible body representation, the runway profile representation, the equations of motion and the solution technique.

The general model is represented as a symmetrical body with either a nose and single strut main landing gear typical of class A through D aircraft. Each landing gear strut is assumed to have point contact with the profile and it is assumed that the main landing gear traverses the same profile as the nose landing gear except at a later time. The model has aerodynamic lift and drag and thrust applied at the aircraft's center of gravity.

The fuselage is free to pitch, plunge and translate horizontally down the runway. In addition to these rigid body degrees of freedom, up to 15 flexible modes of vibration are included. This fuselage motion is controlled by the landing gear strut forces, lift, drag, thrust, and the resisting parameters of aircraft mass and inertia. Figure 1 is a schematic drawing of the mathematical model used for this simulation.

The landing gear struts are non-linear, single acting oleo-pneumatic energy absorbing devices (Figure 2) and are represented in the model as the sum of the three forces, penumatic, hydraulic, and strut bearing friction forces. The pneumatic force, which is the largest of the three is represented by the equation:

$$F_{a} = \frac{PV}{V-S} \tag{1}$$

where:

 F_a = pneumatic strut force

P = the fully extended strut pressure

V = the fully extended strut volume

A =the pneumatic piston area

S = strut stroke

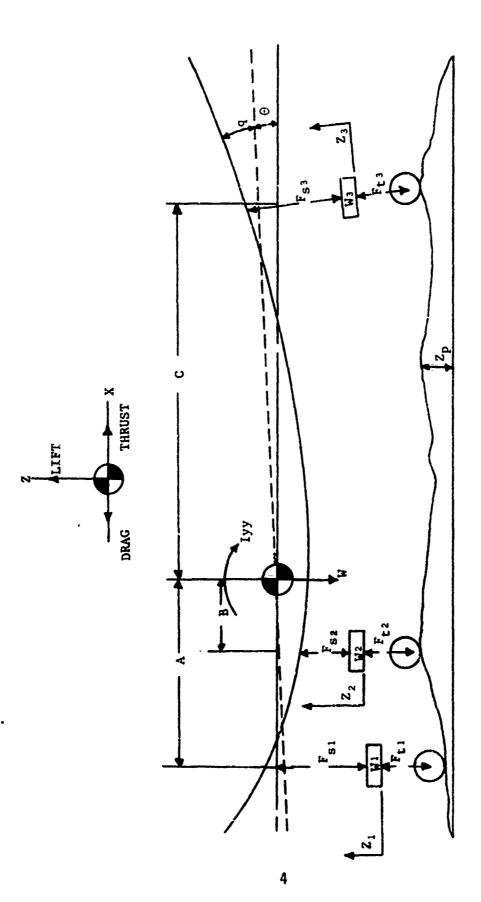


Figure 1 - Mathematical Model used in TAXI Simulation

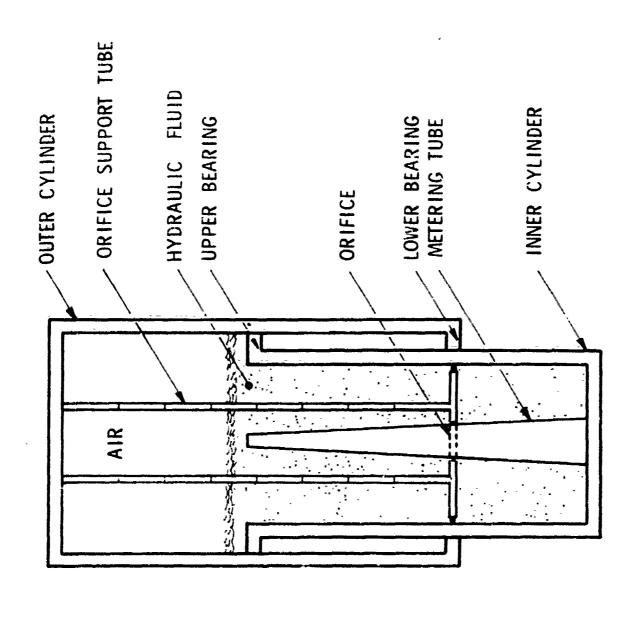


Figure 2. Typical Single Acting Oleo-Pneumatic Landing Gear Strut

The hydraulic or damping force is given by the equation:

$$F_{h} = \frac{P_{h} A_{h}^{3} \dot{S} \dot{S}}{2 (C_{d} A_{o})^{2}}.$$
 (2)

where:

 F_h = hydraulic strut force

 P_h = density of the hydraulic fluid

 A_h = the hydraulic piston area

A_o = effective orifice area (constant orifice minus metering pin area)

 C_d = orifice coefficient (use 0.9)

S = strut piston velocity

The third strut force is the strut bearing friction force and is included in the model only when articulated or asymmetrically loaded struts are being simulated. In symmetrically loaded struts the friction force is neglected (see Reference 1). The following derivation of the friction force was taken from Reference 2.

The force on upper and lower strut bearings due to rolling friction is shown in Figure 3:

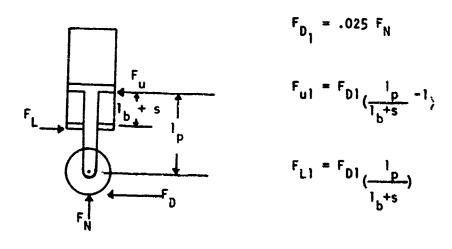


Figure 3. Friction Force Due to Wheel Drag

where:

 F_{n} = landing gear drag force

 F_N = landing gear normal force

Fu, FL = bearing forces at the upper and lower bearings respectively required to balance the lateral loading on the piston

 l_p = the piston length

 1_{b} = the strut fully extended bearing separation

s = the strut stroke

The force on upper and lower strut bearings due to nonperpendicular orientation is represented by Figure 4:

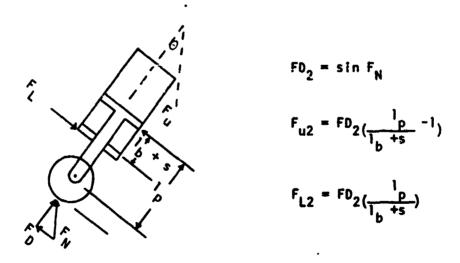
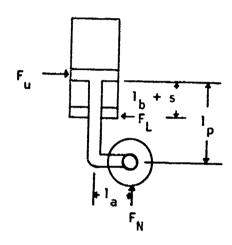


Figure 4. Friction Force Due to Nonperpendicular Orientation

Finally, as represented in Figure 5, the force on the upper and lower strut bearings due to axle offset is:



$$F_{u3} = F_{L3} = \frac{F_N la}{(l_b + s)}$$

Figure 5. Friction Force Due to Axle Offset

For a landing year strut having wheel drag, an angle from the vertical and an axle offset, the total friction force would be as follows:

$$F_{u} = F_{u1} + F_{u2} + F_{u3}$$

$$F_{L} = F_{L1} + F_{L2} \pm F_{L3}$$

$$F_{F} = [\mu_{L} F_{L} + \mu_{u} F_{u} + F_{Fo}] \quad |\dot{s}|$$

where:

F_f = friction force

 $\mu_{\rm U},~\mu_{\rm L}$ = coefficients of sliding friction at the upper and lower bearings, respectively; $\mu_{\rm U}$ = 0.10, $\mu_{\rm L}$ = 0.15

(The lower bearing is generally not as well lubricated as the upper bearing.)

F_o = strut seal friction at zero lateral loading

The tire force is represented by the linear equation

$$F_{t} = k T_{D}$$
 (3)

where:

 $F_t = tire force$

 T_D = tire deflection

k = linear tire spring constant

The runway elevation data is input into the model in two-foot increments, three data points at a time for each landing gear as required. The profile is made continuous by fitting the following polynomial through the three elevation data points and the slope at the end of the previous profile segment:

$$Y(x) = a_1 + a_2x + a_3x^2 + a_4x^3$$
 (4)

where:

 $a_{1,2,3,4}$ = coefficients derived from the elevation and slope data

SECTION III

EQUATIONS OF MOTION AND SOLUTION TECHNIQUE

Equations of Motion:

The differential equations of motion for the mathematical model were derived by application of Hamilton's principle of minimum energy. The general form of these equations is shown below and corresponds to the notation shown in Figure 1.

Rigid Body Equations of Motion

$$\ddot{Z} = (F_{s1} + F_{s2} + F_{s3} + L \sim W)/M_{cg} [c.g., vertical acceleration]$$
 (5)

$$\ddot{Z}_{1} = (\dot{F}_{t1} - F_{s1} - W_{1})/M_{1}$$
 (6)

$$Z_1 = (F_{t1} - F_{s1} - W_1)/n_1$$
 [unsprung landing gear
$$Z_2 = (F_{t2} - F_{s2} - W_2)/M_2$$
 mass acceleration] (7)

$$\ddot{z}_3 = (F_{t3} - F_{s3} - W_3)/M_3$$
 (8)

$$\ddot{\theta} = (F_{s1} A + F_{s2} B + F_{TD} \varepsilon_1 - F_{s3} C) / I_{yy} [pitching acceleration]$$
 (9)

$$\ddot{X} = (F_T - F_{TD} - F_{AD})/(12M_{cg})$$
 [horizontal translation acceleration] (10)

where:

 F_{s1} , F_{s2} , F_{s3} = total landing gear strut forces

 F_{t1} , F_{t2} , F_{t3} = tire forces

 M_{cg} , W, I_{yy} = aircraft mass, weight and pitching inertia

 W_1 , W_2 , W_3 = unsprung landing gear weights

A, B, ε_1 , = monorit arms

L, F_T , F_{TD} , $F_{AD} = 115^{\circ}$. Shoust and tire and aerodynamic drag forces

d F_{AD} act through the center of gravity]

Flexibility Equations of Motion

 $M_i\ddot{q}_i = \xi_{i1}F_{s1} + \xi_{i2}F_{s2} + \xi_{i3}F_{s3} - 2\xi_i\omega_iM_i\ddot{q}_i - \omega_i^2M_iq_i$ for the ith mode (11) where:

M: = the generalized mass

 ξ_{i1} , ξ_{i2} , ξ_{i3} = modal deflections at gear location 1, 2 and 3

 $\omega_i = modal$ frequency

 $S_i = damping factor$

 q_i , q_i , q_i = generalized coordinate and time derivatives

The sign convention corresponding to Figure 1 and the equations of motion is as follows:

Z = Vertical Displacement + up

 $\theta = Pitch + nose down$

q = Deflection Due to Bending + up

X = Horizontal Translation + forward

Solution Algorithm:

The technique used for solving the coupled nonlinear differential equations of motion that describe the simulated aircraft is a threeterm Taylor series. For example, the equation:

$$\ddot{x} = -c\dot{x} - kx \tag{12}$$

The three-term Taylor series representation can be written as:

$$x_{(I+1)} = x_I + \dot{x}_{(I)} (\Delta t) + \ddot{x}_{(I)} = \frac{(\Delta t)^2}{2}$$
 (13)

where: $I = i \rightarrow N$

The values for x, x and x from the previous step are substituted into

equation (13) and a new value for x is obtained. Differentiating equation (13) we obtain for the velocity \dot{x} , the expression

$$\dot{x}_{(1+1)} = \dot{x}_{(1)} + \ddot{x}_{(1)}(\Delta t) \tag{14}$$

The values for \dot{x} and \ddot{x} are then substituted into equation (14) and a new value of \dot{x} is found. This entire process is repeated with the new values of x and \dot{x} to obtain the next point in the solution.

In Section IV Table II identifies and shows the modifications of cards which are necessary for a Class E aircraft. All other data cards remain the same. Table III shows the format for inputing the runway profile data.

The sample problem at the end of this section simulates a Class C aircraft traversing the profile of Taxiway E at the Will Rogers International Airport at a constant speed of 100 feet per second. The sample problem output in order of occurrence is as follows:

TABLE IV Runway Profile Listing

TABLE V List of Input Data Used

TABLE VI One Page of Listed Time History Output

Figure 6 Time History Plot

Class C Aircraft

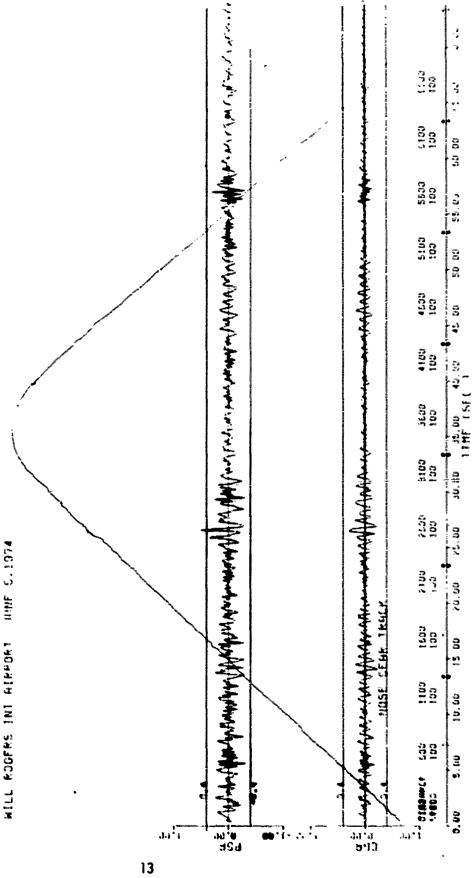


Figure 6 - Calcomp Plottled Results of Sample Problem

SECTION IV

COMPUTER PROGRAM

The computer program, used to predict the dynamic response of the commercial aircraft described in the rext section, is the basic program described in Reference 1 with a few minor changes. These program changes include the capability to simulate strut bearing friction forces, multiple main landing gear struts, root mean square calculations, compressed plot capability, compressed or suppressed printing, and other minor improvements.

Appendix A contains a complete listing of the general computer program for all aircraft except the Class E aircraft. A complete listing for the program used to simulate the Class E aircraft is shown in Appendix B. To simulate a Class B aircraft with the inclusion of strut bearing friction, the separate "TAYLOR" subroutine listed in Appendix C, should be substituted for the "TAYLOR" subroutine included in the general program. If it is desired to run Class B aircraft without strut bearing friction, the general program can be used. Appendix D contains a complete listing of the FORTRAN symbols used.

The following tables I through V' contain the form of the aircraft input data required for an aircraft airfield simulation. The data cards are sequenced as they must appear in the aircraft data deck. For each data card, variable names, definitions, units, card columns, and format field specifications are given.

Table I contains the form of the aircraft data deck for all conventional (Class A through D) landing gear aircraft. These aircraft all have main landing gear struts which are single acting and are non-articulated. Table I also contains the data used in the sample problem at the end of this section.

TABLE |

AIRCRAFT DATA FOR CONVENTIONAL AIRCRAFT

Section 1 (cards 1-5) - General Airplane Data

Card Column	Format	Variable Name	Data for Sample Problem	Definit <u>i</u> on
Card 1				
1-80	8A10	PLANE	Class C	Airplane Being Simulated
Card 2				
1-10 11-20 21-30 31-42	F10.1 F10.1 F10.1 F12.0	W A B MM I	306000. 30. 678. 84700000.	Vehicle Weight (1b) Distance Main Gear to CG (in) Distance Nose Gear to CG (in) Mass Moment of Inertia (1b in sec ²)
Card 3				
1-10 11-20	F10.2 F10.2	PSARM TAILRM	757 637	Distance of Pilot Station to CG (in) Distance of Tail Station to CG (in)
Card 4				
1-10 11-20 21-30	F10.2 F10.2 F10.2	SPEED THRUST TAKEOFF	100 48000. 289.	Initial Velocity of Airplane (ft/sec) Total Airplane Thrust (lb) Airplane Rotation Speed (ft/sec)
Card 5				
1-10 11-20 21-30	F10.4 F10.4 F10.4	CL AREA CD	.603 2890. .03	Lift Coefficient Wing Area (ft ²) Drag Coefficient
		Section	2 (cards 6-11)	- Main and Nose Gear
Card 6				
1-10 11-20 21-30 31-40	F10.2 F10.2 F10.2 F10.2	HH HN SXM SXN	1659. 432. 2. 1.	Unsprung Weight of Each Main Gear (1b) Unsprung Weight of Nose Gear (1b) Number of Main Gear Struts Number of Nose Gear Struts

Card		Varíable	Data for Sample	
Column	Format	Name	Problem	Definition
1-10	F10.5	AHN	13.91	Hydraulic Piston Area Nose (in ²)
11-20	F10.5	AAN	19.64	Preumatic Piston Area Nose (in2)
21-30	F10.5	AHM	66.80	Pydraulic Piston Area Main (in ²)
31-40	F10.5	AAM	78.47	Pneumatic Piston Area Main (In ²)
Card 8				
i-lō	Ē10.5	PAON	265.	Nose Strut Préjoad Pressure (1b/in²)
11-20	F10.5	FAOM	243.	Main Strut Preload Pressure (lb/in²)
21-30	F10.5	VON	335.	Fully Extended Nose Strut Air Volume (in3)
31-40	F10.5	VOM	1816.6	Fully Extended Main Strut Air Volume (in3)
41-50	F10.5	OAM	3.14	Orifice Area Main (in ²)
51-60	F10.5	OAN	1.23	Orifice Area Nose (in ²)
Card 9				
1-10	F10.3	SLM	91.0	Distance from Axle to CG Waterline Main Gear Strut Unloaded (in)
11-20	F10.3	SLN	91.0	Distance from Axle to CG Waterline Nose Gear Strut Unloaded (in)
Card 10				
ì-10	F10.1	TSM	25050.	Main Tire Spring Constant Per Strut (1b/in)
11-20	F10.1	TSN	13000.	Nose Tire Spring Constant Per Strut (1b/in)
Card 11				
1-10	F10.5	DX	.001	Integration Step Size
Card 12				
1-5	15	1 FPLOT	0	0-Plot: 1-No Plot
6-10	15	IFLIST	ŏ	O-List; 1-No Plot
		Section 3 (c	ards 13-16)-M	Metering Pin Description
Card 13				
1-5	15	NSCN	7	Number of Slope Changes Nose Gear

Card Column	Format	Variable Name	Data for Sample Problem	Definition
*Card 14A	, 14B,			•
1-10	F10.3	STROKN (1)	*	Stroke Corresponding to Metering Pin Diameter, Nose Gear
11-20	F10.3	PINDN (1)	*	Metering Pin Diameter, Nose Gear (in)
Card 15				
1-5	15	NSCM	9	Number of Slope Changes Main Gear
*Card 16A	, 16B,			
1-10	F10.3	STROKM (I	,	Stroke Corresponding to Metering Pin Diameter, Nose Gear
11-20	F10.3	PINDM (I)	*	Metering Pin Diameter, Main Gear (in)
		Section	4 (cards 17-	19)-Flexibility Data
Card 17				
1-5	15	NFM	10	Number of Flexible Modes
**Card 18	A, 18B			
1-10	F10.3	SIMAIN (I) * *	Mode Shape Deflection Main Gear
11-20	F10.3	SINOSE (I		Mode Shape Deflection Nose Gear
21-30	F10.3	SICG (1		Mode Shape Deflection CG
31-40	F10.3	SITAIL (I		Mode Shape Deflection Tail Station
41-50	F10.3	SIPS (I) **	Mode Shape Deflection Pilot Station
**Card 19	A, 19B,	•		
1-15	F15.2	GM (1)	**	Generalized Mass (1b sec ² /in)
16-25	F10.3	OMEGA (1)	**	Modal Frequency (rad/sec)

^{*}One card is required for each stroke-metering pin combination read into the program.

Data for Sample Problem is shown in Table V.

^{**}One card is required for each flexible mode. Data for Sample Problem is shown in Table V.

TABLE II

INPUT DATA CHANGES FOR CLASS E AIRCRAFT

Card Column	Format	Variable Name	Definition
Card 2			
1-10 11-20 21-30	F10.1 F10.1	₩ A B	Vehicle Weight (lbs) Distance Front Main Gear to CG (in) Distance Nose Gear to CG (in)
31-40 41-52	F10.1 F12.0	C MMI	Distance Rear Main Gear to CG (in) Mass Moment of Inertia (lbin sec ²)
Card 6			
1-10 11-20 21-30 31-40 41-50	F10.2 F10.2 F10.2 F10.2 F10.2	WM WN SXM SXN WRM	Unsprung Weight of Each Front Main Gear (lbs) Unsprung Weight of Nose Gear (lbs) Number of Main Gear Struts Number of Nose Near Struts Unsprung Weight of Each Rear Main Gear (lbs)
Card 7			
1-10 11-20 21-30 31-40 41-50 51-60	F10.5 F10.5 F10.5 F10.5 F10.5	AHN AAN AHM AAM AHRM AARM	Hydraulic Piston Area Nose (in ²) Pneumatic Piston Area Nose (in ²) Hydraulic Piston Area Front Main (in ²) Pneumatic Piston Area Front Main (in ²) Hydraulic Piston Area Rear Main (in ²) Pneumatic Piston Area Rear Main (in ²)
Card 8			
1-10 11-20 21-30 31-40 41-50 51-60 61-70 71-80	F10.5 F10.5 F10.5 F10.5 F10.5 F10.5 F10.5	PAON PAOM VON VOM OAM OAN PAORM VORM	Nose Strut Preload Pressure (lbs/in²) Front Main Strut Preload Pressure (lbs/in²) Fully Extended Nose Strut Air Volume (in³) Fully Extended Front Main Strut Air Volume (in³) Orifice Area Front Main (in²) Orifice Area Nose (in²) Rear Main Strut Preload Pressure (lbs/in²) Fully Extended Rear Hain Strut Air Volume (in³)
Card 10			
1-10 11-20 21-30 31-40	F10.1 F10.1 F10.1 F10.1	TSM TSN TSRM OARM	Front Main Tire Spring Constant Per Strut (1bs/in) Nose Tire Spring Constant Per Strut (1bs/in) Rear Hain Tire Spring Constant Per Strut (1bs/in) Orifice Area Rear Main (in ²)

Runway Profile Magnetic Tape

The runway profile is read into the program from a magnetic tape or permanent file. The format for this tape is shown in Table III.

TABLE III
RUNWAY PROFILE MAGNETIC TAPE

Column	Format	Variable Name	Definition
Read 1			
1-80	8A10	SITE	Runway Profile and Direction
Read 2			
1-6	16	NPTSS	Number of Runway Elevation Points
*Read 3, 4	, N+2		
1-70	10F7.3	ELEV	Runway Profile Data

 ± 0 ne read required for every ten runway profile elevation points.

Figure 7 contains a schematic diagram of the source deck setup for all aircraft simulations.

In order to simulate Class B aircraft with the strut friction force included, changes must be made to the basic program. This change is required as a result of the main and nose landing gear having a significant angle from the vertical and an axle offset on the main landing gear. The Class B aircraft source deck is formed by removing the subroutine Taylor from the basic source deck and replacing it with the Taylor shown in Appendix C.

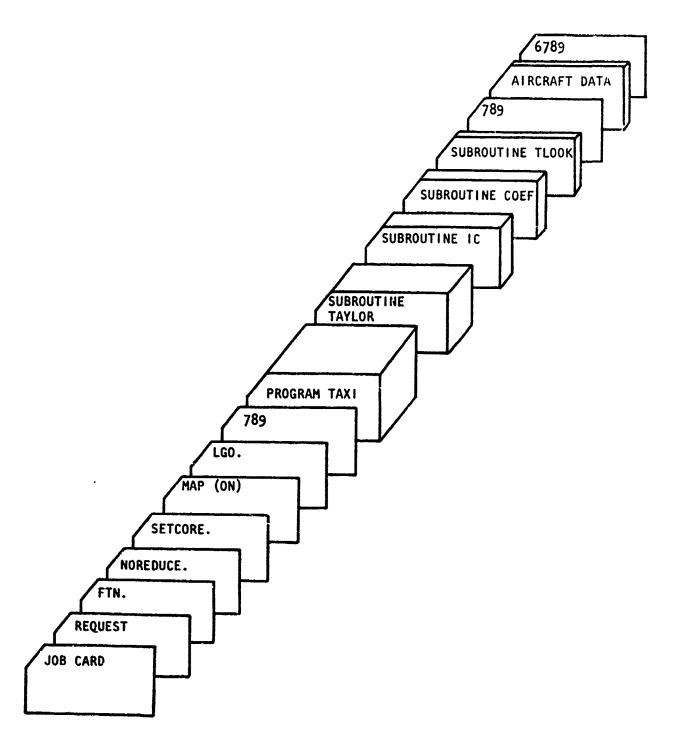


Figure 7 - Source Deck Setup for All Aircraft

TABLE IV - Profile Data of Will Rogers International Airport's Taxiway E used in the Sample Problem

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3.63901	3.63281	3.59062	3.53642	3.49423	3.45203	3.38584	3.41364	3.34945	3.36725	9869
3.34906	3,34286	3,31267	3.31847	3.24326	3.25808	3.16769	3,13569	3.16750	3.17330	2007
3.09511	3.07691	3.14272	3.07652	3.01033	2,98013	2.93794	2.83374	2.47755	2.65935	7020
2.02916	2.83496	2,81677	2.79857	2.79238	2.75018	2.73199	2,73179	2.65960	2.65340	0404
2.65921	2.64161	2.61082	2.64062	2.64643	2.56423	2.65804	2.63984	2.65765	2.57945	7 060
2.56126	2.54306	2.51287	2.48267	2,42848	2.45628	2.42809	2, 337 89	2.40370	2,33750	7 080
2.27131	2.27711	2.27092	2.30072	2.23453	2.31233	2.23414	2.22794	2,19775	2.23955	7 100
2.20936	2,22716	2.14897	2.20277	2.16358	2.14234	2,13619	2,01399	2.05140	2.03900	7120
2.06340	2.08121	2. 5101	2.04482	1.97862	1.47243	2,00223	2.03234	2.01354	2.03165	7140
2.01345	2.06726	2.10966	2.13667	2,12067	2.11448	2,07228	2.04009	2,03589	2.01770	7160
2.1150	1.90931	1.91511	1.92092	1.85472	1.84053	1.78233	1.75414	1.72234	1.73375	7180
1.63755	1.66736	1.63716	1.54097	1.57677	1.51058	1.51638	1.45219	1.44393	1.41350	7 200
1.37160	1.53941	1.29921	1.31702	1,34682	1,32863	1.33443	1.22024	1.22604	1.17185	7 22 6
1.21365	1.14746	1.22526	1.19507	1.14087	1.11068	1.15248	1.17029	1,12803	1.15790	7.240
1.16370	1.16951	1.16331	1.16912	1.09092	1.09673	1.04253	1,05034	1.30014	1.02395	7.260
1.01775	1.01156	1.61736	1,02317	1.05297	1.10678	1.06458	1,03439	1.11219	1.07000	7 260
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-1.30965	-1.27985	-1.27464	-1.22024	-1.22643	-1.23263	-1.25082	-1,25742	-1.27521	-1.29341	7529

TABLE V - Airplane Data for Sample Problem

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TABLE V1 - Typical Page of Tested Output Taken from the Results of the Sample Problem

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SECTION V

RESULTS

The mathematical model and computer program presented in this report is capable of simulating five classes of commercial jet aircraft. Classification is made on the basis of gross weight as follows:

Class	A	Less tha	n 150	,000	1b	
Class	В	150,000	- 300	,000	1b	
Class	C	300,000	- 450	,000	1b	
Class	D	450,000	- 600	,000	1b	
Class	E	Greater	than	600,0	000	16

The data used to represent these aircraft and typical simulations using the data for each class of aircraft is presented in this section.

The data set for each aircraft class contains a general configuration, (Figures 8, 11, 14, 17, and 20), a description of input variable fortran mames, (Tables VII, IX, XI, XIII, and XV), two pages of input data (Tables VIII, X, XII, XIV, and XVI), and a set of tire deflection curves, (Figures 9, 10, 12, 13, 15, 16, 18, 19, 21, and 22), for both main and nose landing gears. The first page of input data contains all of the rigid body airplane and landing gear data. The second page of data contains the aircraft's modal data and the aircraft's initial conditions as computed by TAXI.

The aircraft data presented was used to simulate each aircraft taking off from two separate profiles, Will Rogers International and Dulles International Airports. The calcomp plotted results are shown in Figures 23 through 32. It is evident that all airplanes responded to the prominent bump which occurred at approximately 2700 feet on the Will Rogers profile, although some to larger degree than others. With the exception of this one bump it is difficult to correlate runway roughness to the response of all aircraft. Some airplanes responded to a certain section of a profile while others did not. Some airplanes responded predominately in pitch such as the Class C and D aircraft while others responded in pitch and plunge such as the Class A and B aircraft. This points out the significance of such parameters as gear stiffness, degree of coupling between the rigid body is seen gear spacing and others.

For all aircraft classes except Class B the rms value of the Pilot's station vertical acceleration was less over the Dulles profile than that of the Will Rogers profile. For all aircraft classes except Class B and

D, the center of gravity vertical acceleration rms level is less for the Dulles profile. For these three exceptions, the rms level was the same for both profiles. From a purely response standpoint then, it can be said that the Dulles International runway profile is smoother than the Will Rogers International profile.

Figures 33 and 34 show the difference in response of Class B aircraft with and without strut bearing friction included in the simulation. The simulation for both runs were at a constant speed of 100 feet per second over the Will Rogers profile. The center of gravity rms level was increased with the inclusion of strut friction while it was reduced slightly at the pilot's station. The jerky motion evidenced by the response at the cg was expected and was caused by the constant "locking up" of the struts due to the binding forces on the upper and lower bearing surfaces of the landing gear struts. It is more evident at the cg because most of the aircraft's weight, and resulting strut forces, is on the main landing gear which is closest to the aircraft's cg.

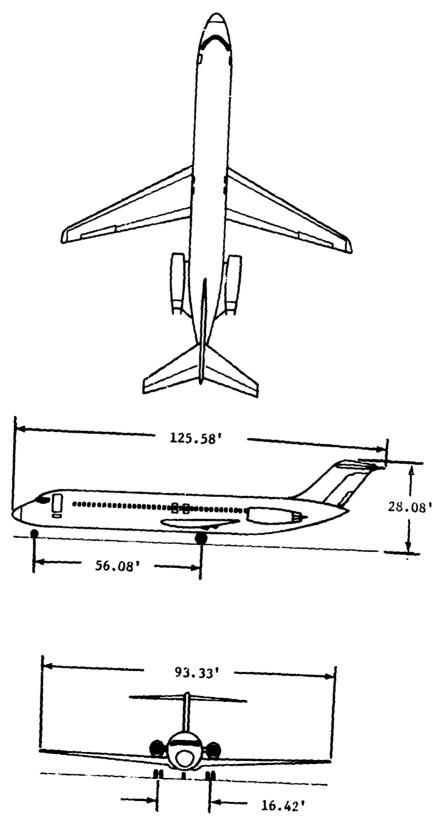


Figure 8 - Class A Aircraft General Configuration

TABLE VII - List of Input Data Fortran Names

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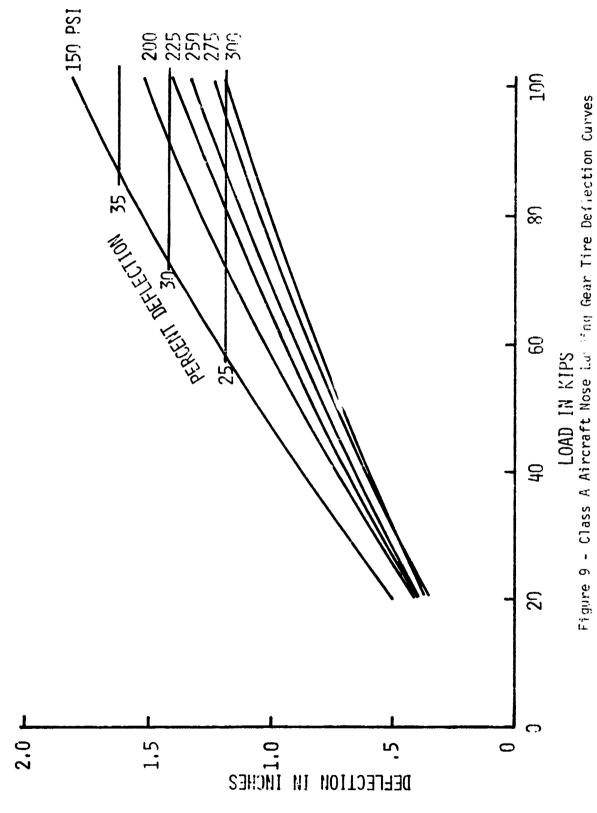
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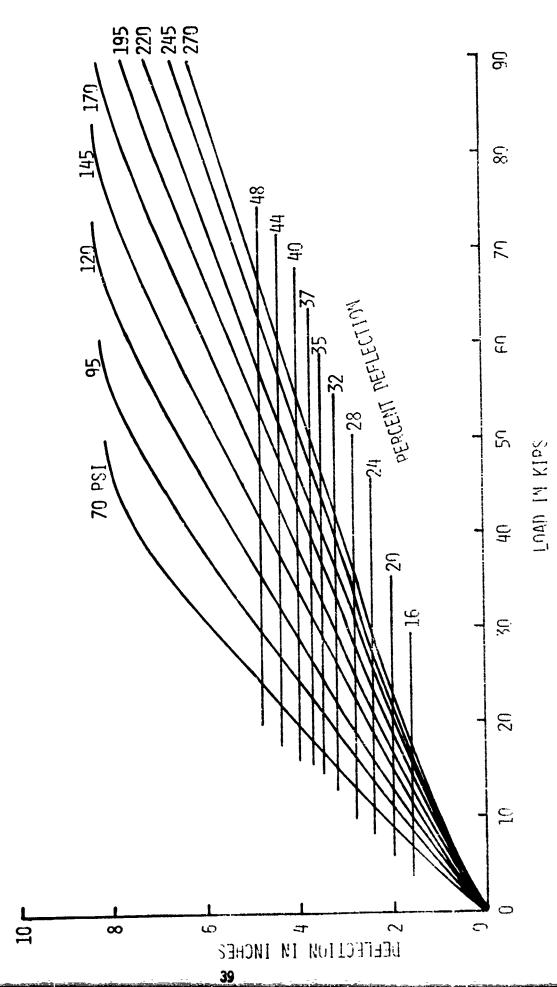


Figure 10 - Class & Aircraft Main Landir (Sear line Deflection Curves

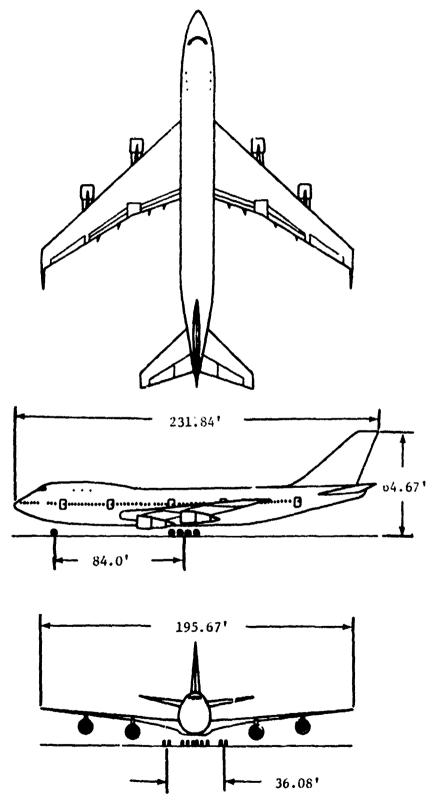


Figure 11 - Class E Aircraft General Configuration

TABLE IX - List of Input Data Fortran Names

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TABLE X - List of Data Used to Simulate Class E Aircraft

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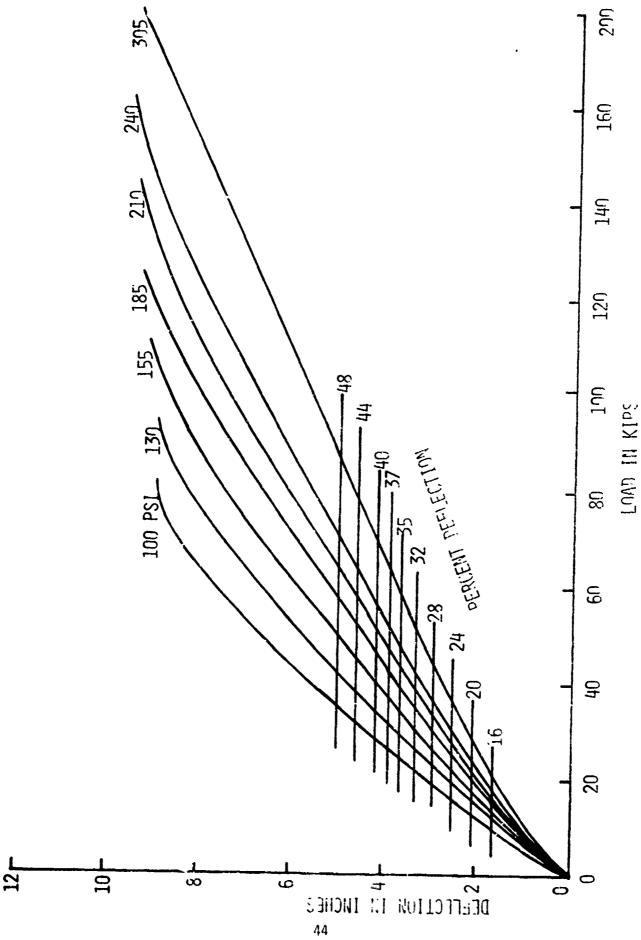


Figure 12 - Class E Aircraft Mose Landing Gear Tire Deflection Curves

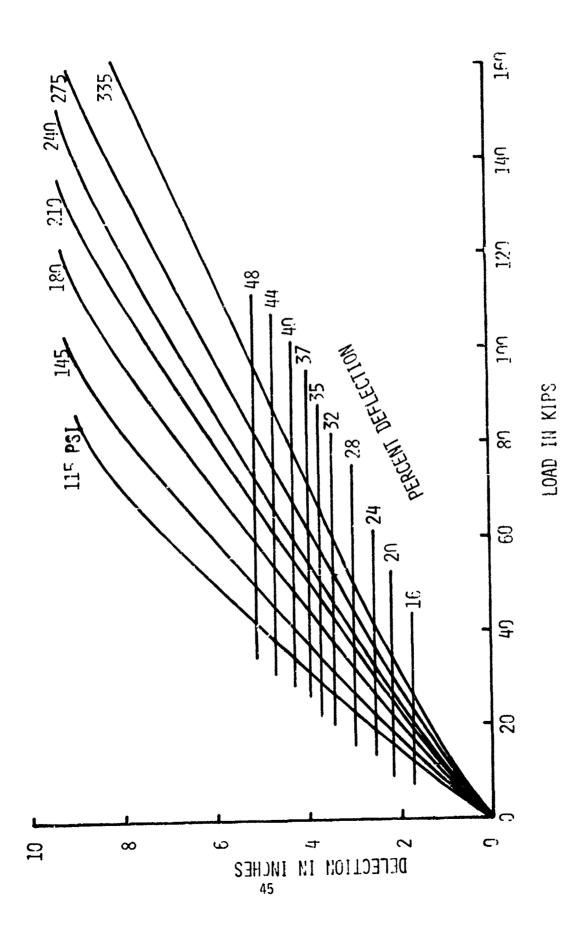
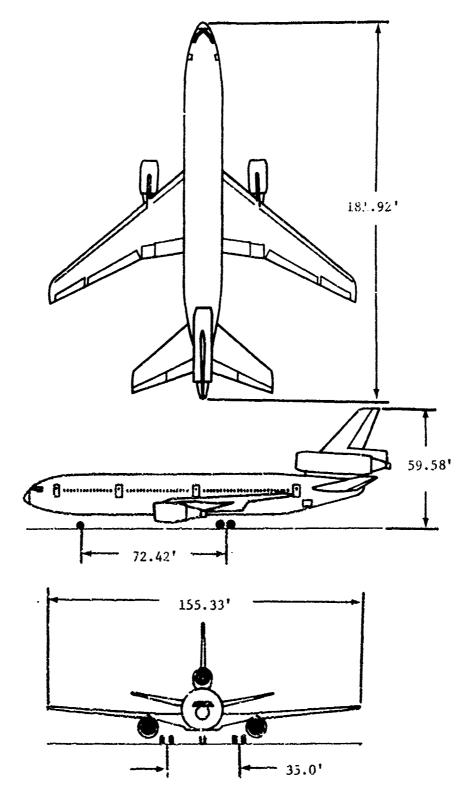


Figure 13 - Class E Aircraft Main Landing Gear Tire Deflection Curves



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Figure 14 - Class D Aircraft General Configuration 46

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TABLE X'! · List of Data Used to Simulate Class D Aircraft

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...... GENERAL AIRCRAFT DATA

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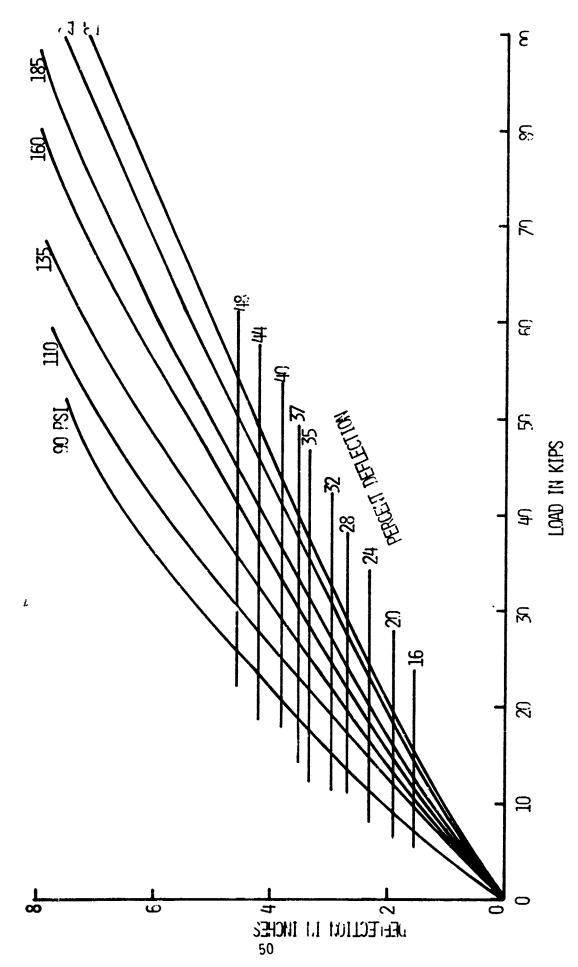
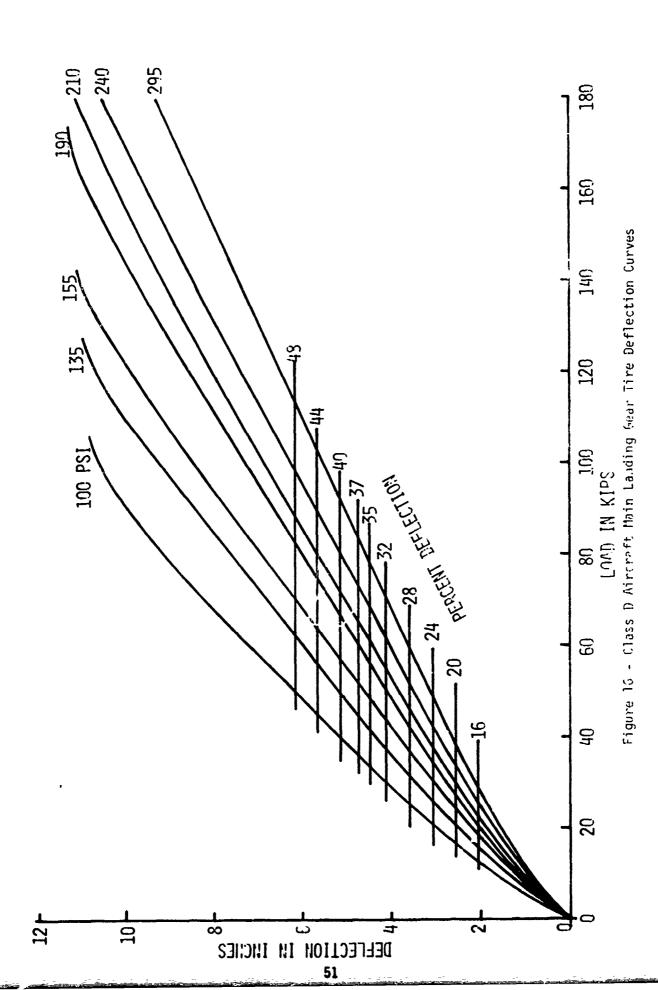


Figure 15 - Class D Aircraft Landing Gear Tire Deflection Curves

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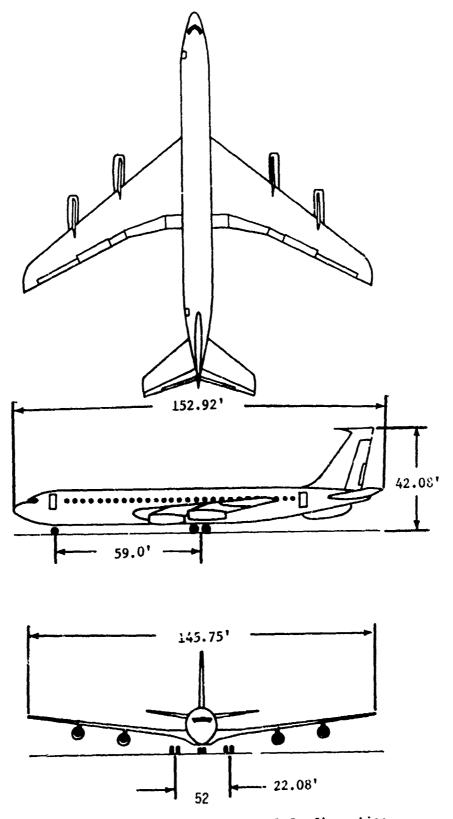


Figure 17. Class C Aircraft General Configuration

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TABLE XIV - List of Data Used to Simulate Class C Aircraft

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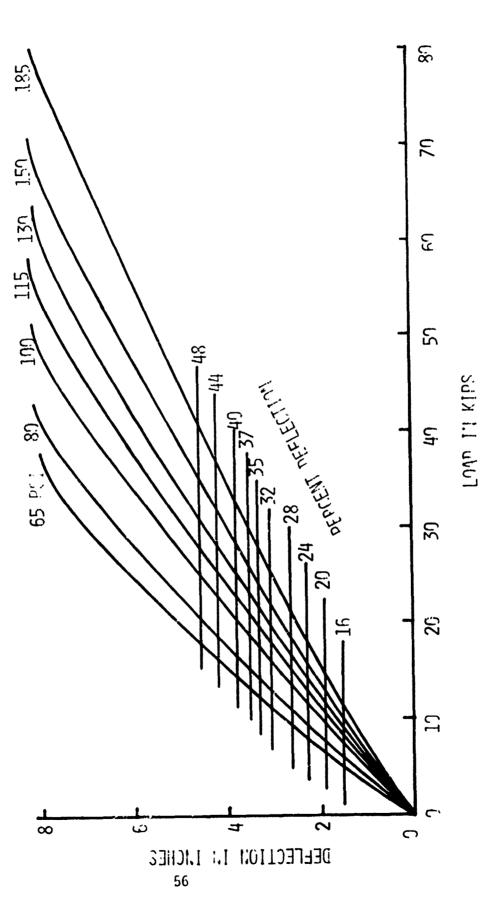


Figure 13. Class C Aircraft Nose Landing Gear Tire Deflection Lurves

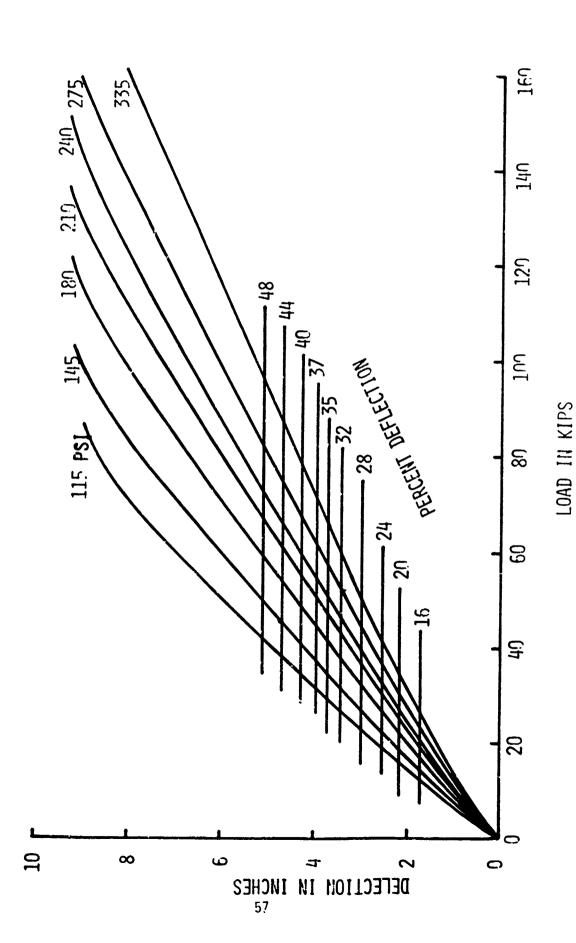
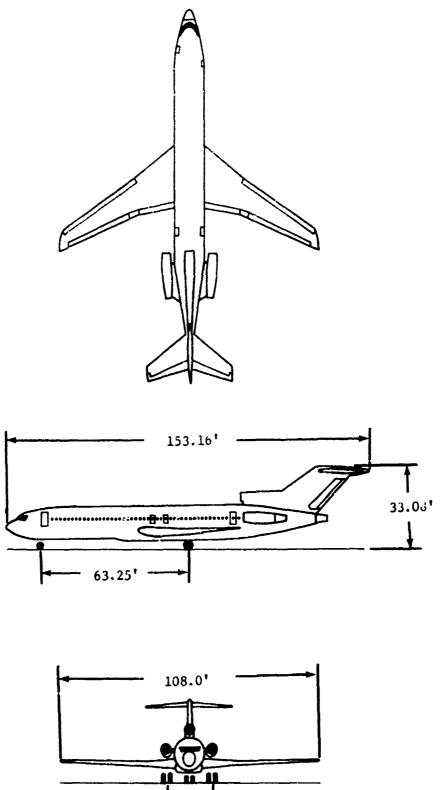


Figure 19. Class C Airrraft Main Landin, Jar Tire Deflection Curves



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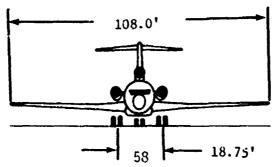


Figure 20. Class B Aircraft General Configuration

TABLE XV - List of Input Data Fortran Names

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TABLE XVI - List of Data Used to Simulate Class B Aircraft

****** GENERAL AIRCRAF! DATA *******

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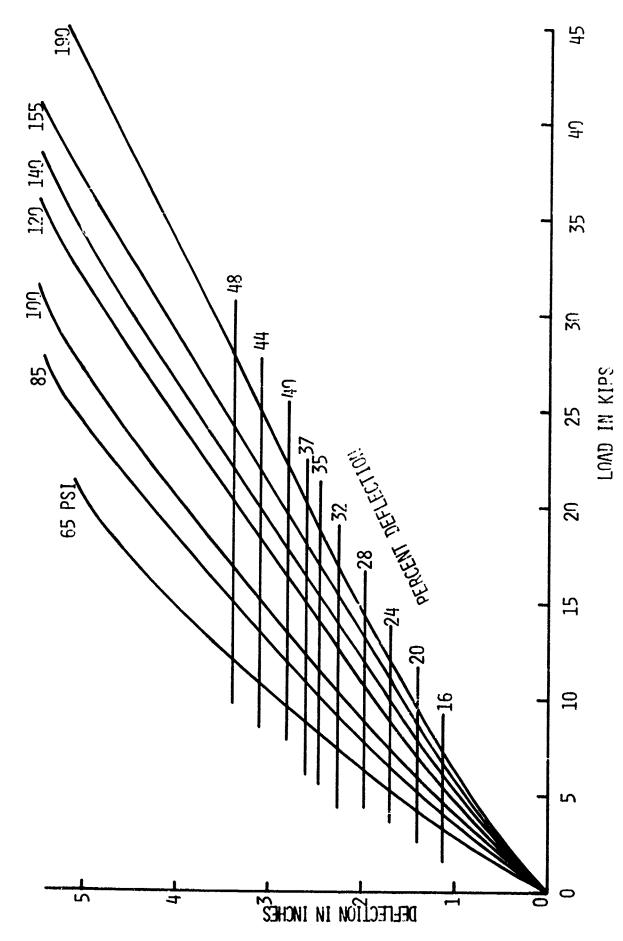
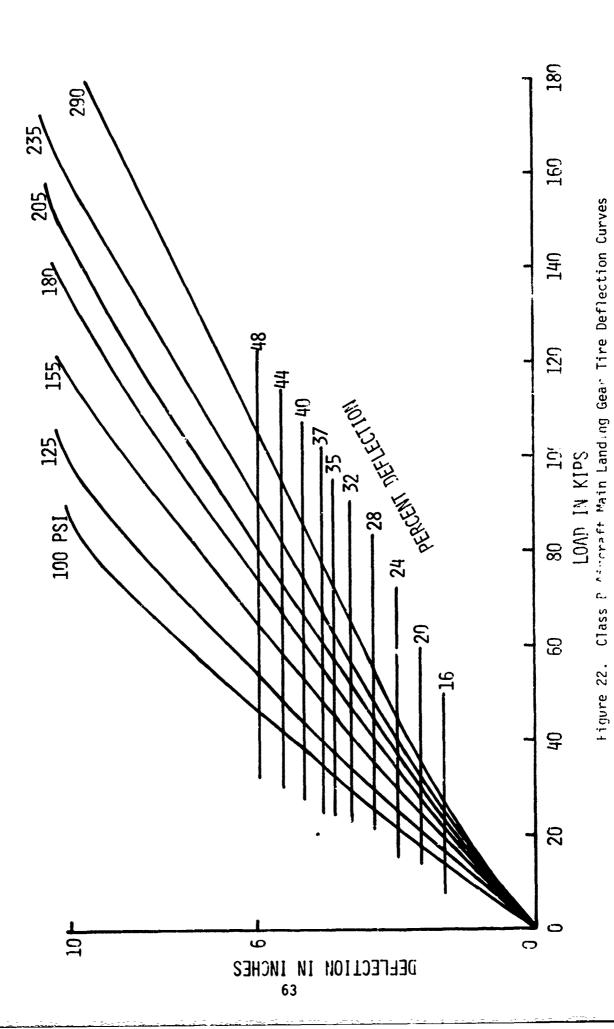
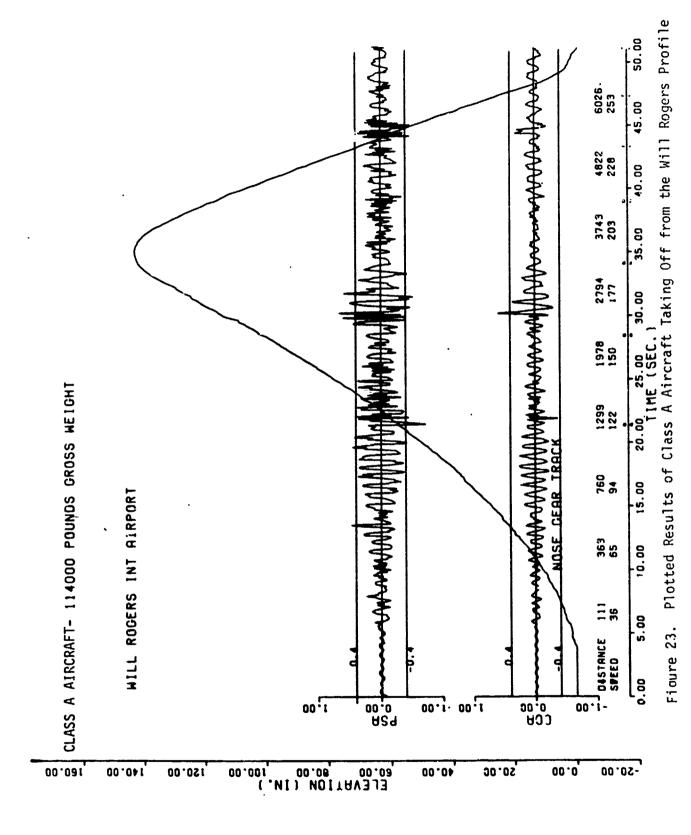


Figure 21. Class B Aircraft Nose Landing Gear Tire Deflection Curves





CLASS A AIRCRAFT 114000 POUNDS GROSS WEIGHT

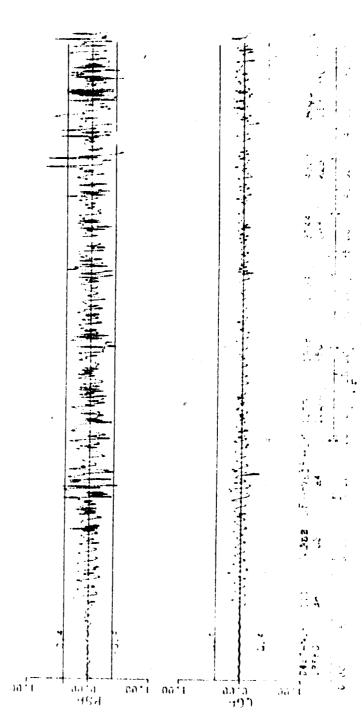
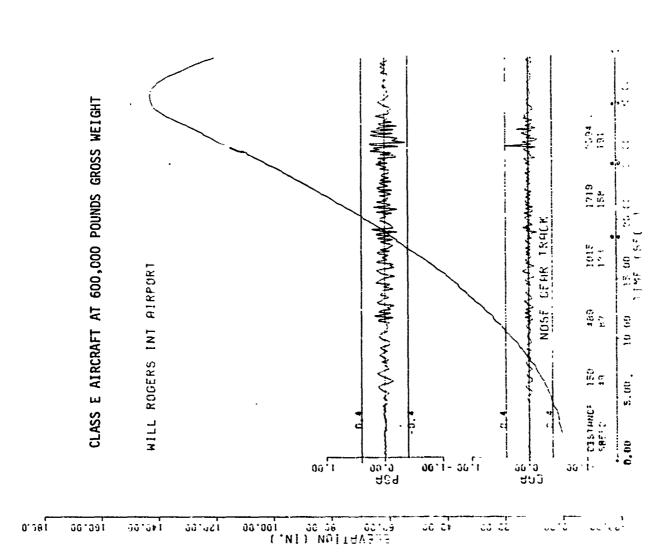


Figure 24. Plotted Results of Class A Aircraft Taking Off from the Dulles Profile



Plotted Results of Class E Aircraft Taking Off from the Will Rogers Profile Figure 25.

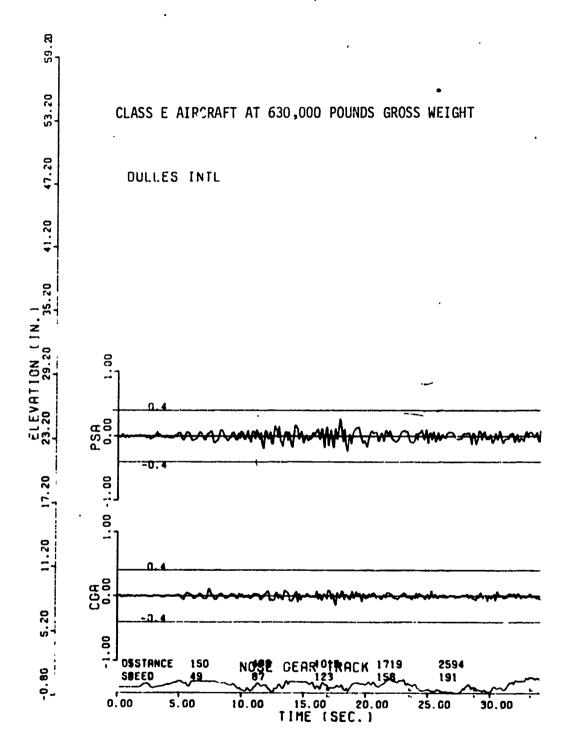
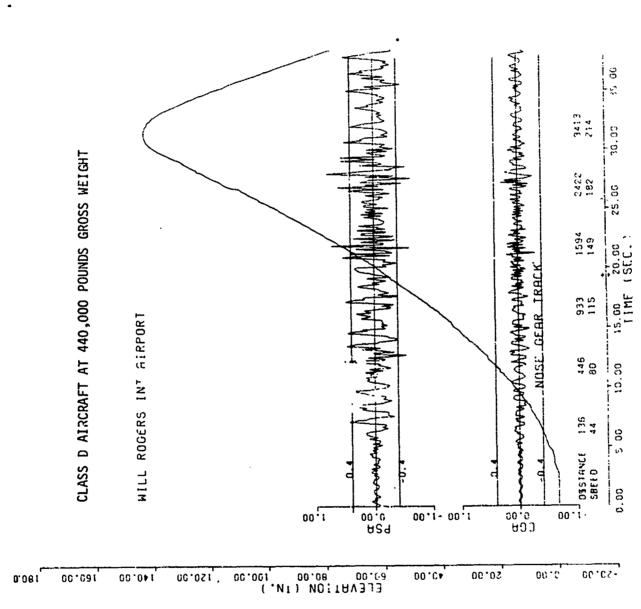
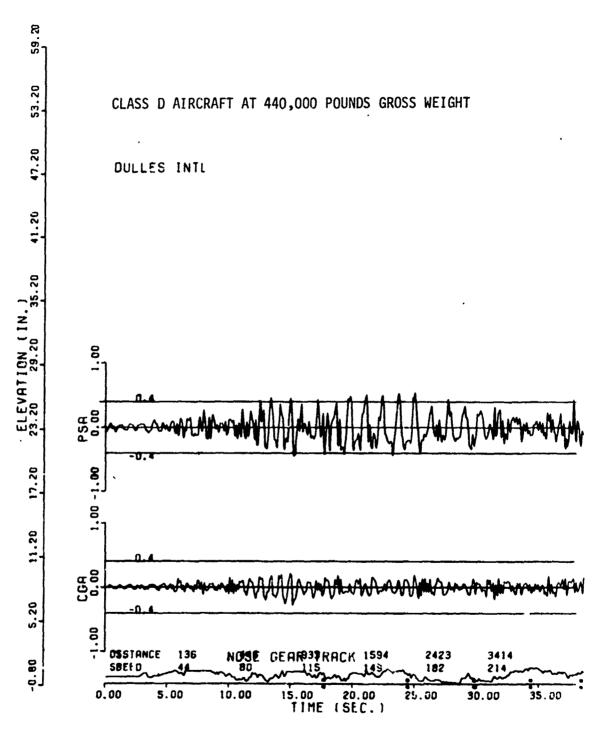


Figure 26. Plotted Results of Class E Aircraft Taking Off from the Dulles Profile



Plotted Results of Class D Aircraft Taking Off from the Will Rogers Profile riαure 27.



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Figure 28. Plotted Results of Class D Aircraft Taking Uff from the Dulles Profile

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Figure 29. Plotted Results of Class C Aircraft Taking Off from the Will Rogers Profile

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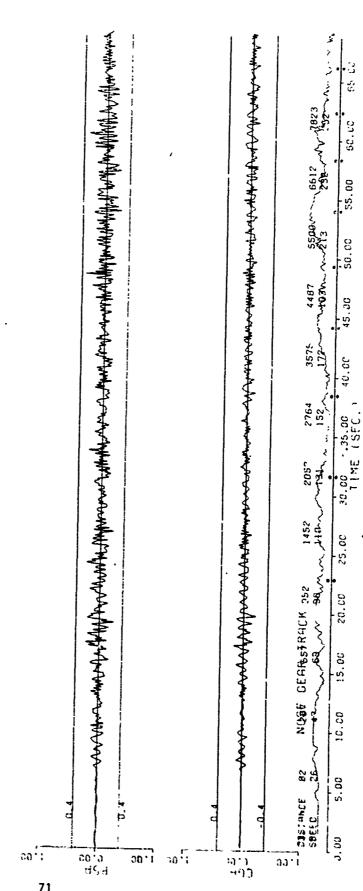


Figure 30. Plotted Results of a class C Aircraft Taking Off from the Dulles Profile

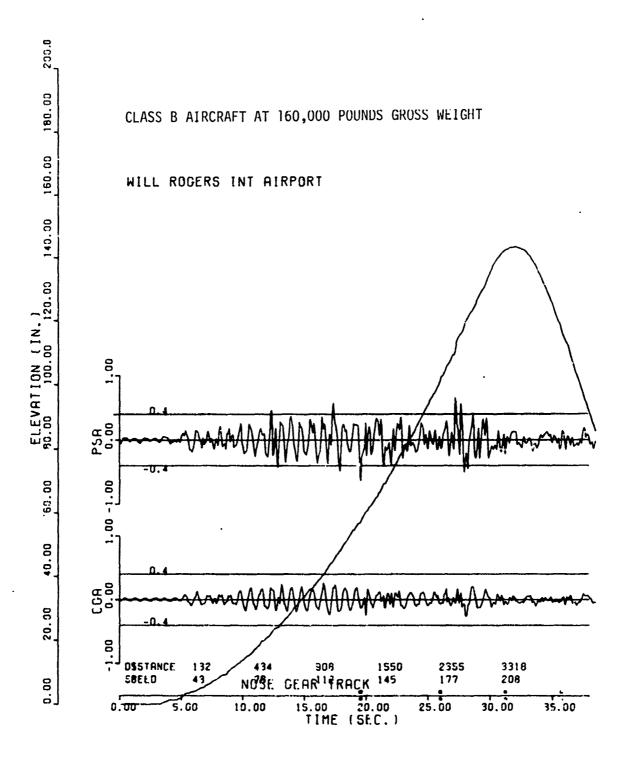


Figure 31. Plotted Results of a Class B Aircraft Taking Off from the Will Rogers Profile

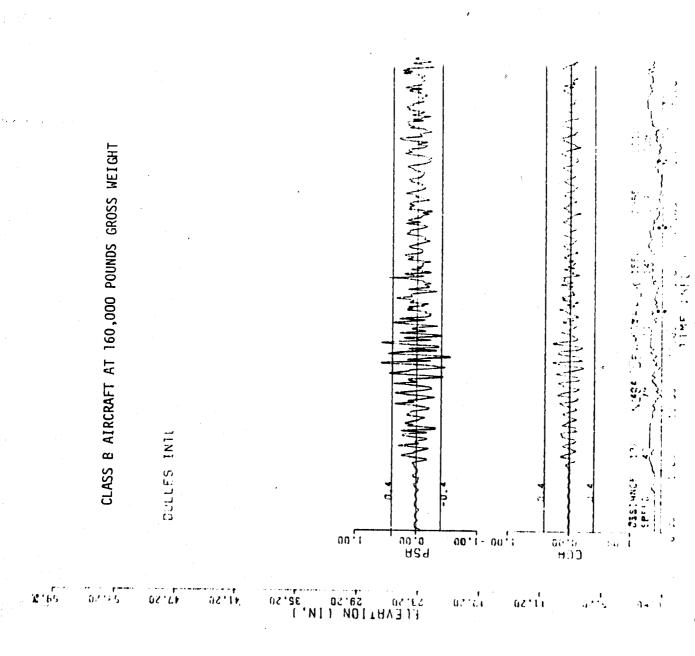


Figure 32. Plotted Results of a Class B Aircraft Taking Off from the Dulles Profile

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CLASS B AIRCRAFT AT 160,000 POUNDS GROSS WEIGHT

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Figure 33. Plotted Results of a Class B.Aircraft During Taxi over the Will Rogers Profile with Strut Friction Included

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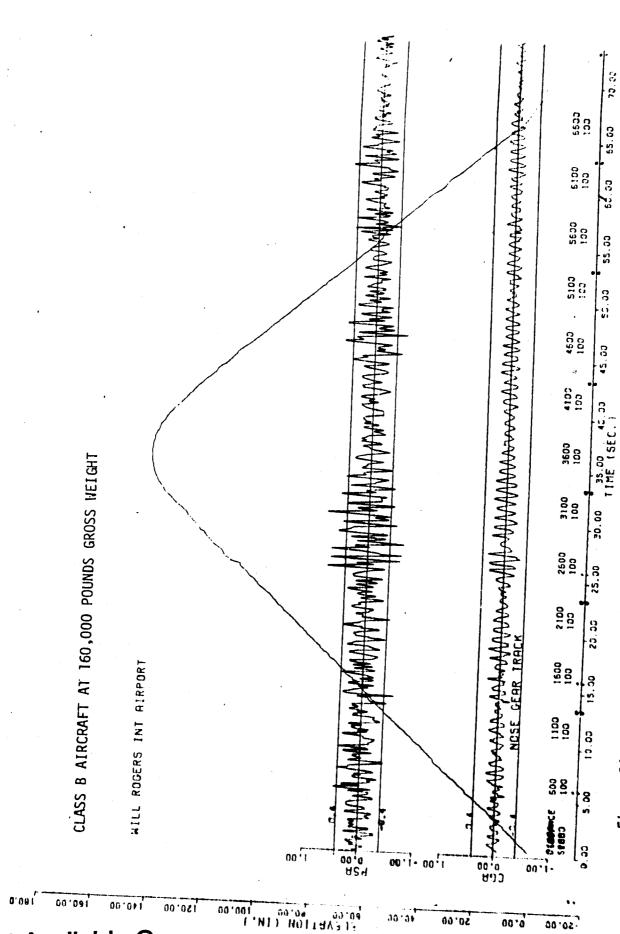


Figure 34. Plotted Results of a Class B Aircraft Dusing Taxi over the Will Rogers Profile without Strut Friction Included

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SECTION VI

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CONCLUSI INS

Data have been collected and reduced to the form required by the computer program "TAXI" for simulation of five classes of commercial jet aircraft as follows:

Aircraft Class	Gross Weight Range-Pound
Class A	Less than 150,000
Class B	150,000 - 300,000
Class C	300,000 - 450,000
Class D	450,000 - 600,000
Class E	Greater than 600,000

Each of these aircraft has been successfully simulated traversing the profiles of Will Rogers International Airport in Oklahoma City, Oklahoma and Dulles International Airport in Washington DC. Results of these simulations indicate that aircraft response to runway roughness is highly dependent on aircraft parameters such as gear stiffness, gear spacing and the degree of coupling between the rigid body modes of vibration, as well as the degree of runway roughness.

The addition of the strut bearing friction forces in the simulation of Class B aircraft has a small effect on the vertical acceleration level at the pilot's station.

REFERENCES

- 1. Gerardi, A. G., Lohwasser, A. K., <u>Computer Program for the Prediction of Aircraft Response to Runway Roughness</u>, AFWL-TR-73-109, Volume I and II, Air Force Weapons Laboratory, Kirtland AFB, New Mexico, September 1973.
- Chance Vought Corporation, A <u>Rational Method for Prediction A Lighting Gear Dynamic Loads</u>, ASD-TDR-62-555, Aeronautical Systems Division, Wright-Patterson AFB, Ohio, Cecember 1963.

APPENDIX A

COMPUTER LISTING FOR THE GENERAL COMPUTER PROGRAM CALLED "TAXI"

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APPENDIX B

COMPUTER LISTING OF "TAXI" USED TO SIMULATE CLASS E ATRORAFT

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APPENDIX C

COMPUTER LISTING OF SUBROUTINE TAYLOR USED TO INCLUDE BEARING FRICTION IN THE STRUT FORCE

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APPENDIX D

FORTRAN SIMBOL DEFINITIONS

This appendix contains an alphabetical listing of the Fortran variables used in the program "TAXI" categorized by the subroutine in which they are defined. In cases where a variable is defined in two or more subroutines, it is listed under the subroutine in which it is used most often. Some symbols used in the Class E Aircraft computer code are not listed. These variables are those which have been formed by adding an R to a variable name which is contained in the basic "TAXI" computer code. The R refers to the rear set of main gear.

FORTRAN SYMBOL DEFINITIONS

TAXI

SYMBOL	DEFINITION
A	Distance from CG to front main gear
AAM	Pneumatic area, main gear
AAN	Pneumatic area, nose gear
AHM	Hydraulic area, main gear
AHN	Hydraulic area, nose gear
AM	Coefficient of polynomial fit to runway profile segment, rear main gear
AN	Coefficient of polynomial fit to runway profile segment, nose gear
AREA	Aircraft wing area
8	Distance from CG to mose gear
ВМ	Coefficient of polynomial fit to runway profile segment, rear main gear
BN	Coefficient of polynomial fit to runway profile segment, nose gear
C	Distance from CG to rear main gear (Class E simulation only)
CD	Coefficient of drag
CGACC	Array containing CG accelerations for Calcomp plot
CGOUT	Total CG acceleration
CL	Coefficient of lift
CM	Coefficient of polynomial fit to runway profile segment, rear main gear
CN	Coefficient of polynomial fit to runway profile segment, nose gear

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Symbol .	DEFINITION
LD	Counting variable for runway profile input
LD1	Counting variable for runway profile output listing
LL	Subscript variable for storage of pilot station acceleration time history
LLL	Subscript variable for storage of aircraft speed and distance for Calcomp plot
LPRIN	Runway distance for runway profile listing
LSD	Counting variable for runway profile input
LSD1	Counting variable for runway profile listing
M	Counting variable for printing out output header first time
MCG	Mass of entire aircraft
MGM	Integer truncation of total simulation time
HH	Mass of unsprung portion of one main landing gear
mi.	Pitching moment of inertia about aircraft center of gravity
MN	Mass of the unsprung portion of the nose landing gear
MRM	Length of runway divided by 1000 feet
MFM	Number of flexible modes
NN	Subscript variable for CG acceleration time history
NPTSS	Number of runway profile points
NSCM	Number of slope or area changes on main strut metering pin
NSCN	Number of slope or area changes on nose strut metering pin
NTRUN	Defines run as taxi or takeoff
N10	Index variable for normalization of runway profile
OAM	Area of orifice hole, main gear
OAN	Area of orifice hole, nose gear

SYMBOL	DEFINITION
OMEGA	Array of flexible mode frequencies
PAOM	Preload pressure of main gear strut
PAON	Preload pressure of nose gear strut
PINDM	Array containing main gear metering pin diameters for conventional aircraft and net orifice areas for aircraft with metering tubes or flutted metering pins
PINDN	Array containing nose gear metering pin diameters for conventional aircraft and net orifice areas for aircraft with metering tubes or flutted metering pins
PLANE	Aircraft being simulated
PP	Counting variable for storage of distance and speed for Calcomp plot
PROF	Runway profile time history elevations
PROF10	PROF (NN+2)X10
PSA	Pilot station acceleration .
PSACC	Array containing pilot station acceleration time history
PSARM	Distance from pilot station to CG
Q	Array of non-dimensional time dependent coordinates which weight the amount of motion due to each flexible mode in the total motion of the aircraft
QD	Time derivative of Q
QDD	Time derivative of QD
QDDCG	CG acceleration due to flexible motion
QDDPS	Pilot station acceleration due to flexible motion
QDDTAL	Tail station acceleration due to flexible motion
REACTM	Static, total force at main gear
REACTN	Static, total force at mose gear
RM	Incremented variable for determining position of runwav markers

SYMBOL	DEFINITION
RMARK	Array containing runway markers positions
SICG	Mode shape deflection of CG
SIMAIN	Mode shape deflection at main landing gear
SINOSE	Mode shape deflection at nose landing gear
SIPS	Mode shape deflection at pilot station
SITAIL	Mode shape deflection at tail station
SITE	Location of runway
SLM	Distance from CL of main gear axle to CG of aircraft with strut fully extended
SLN	Distance from CL of mose gear axle to CG of aircraft with strut fully extended
SLP	Overall slope of runway profile
SPEED	Initial speed of aircraft
SSPLOT	Array of velocity of aircraft for Calcomp plot
STOREI	Temporary storage space for CG accelerations
STORE2	Temporary storage space for CG accelerations
STORE3	Temporary storage space for pilot station accelerations
STORE4	Temporary storage space for pilot station accelerations
STROKM	Array of strut stroke values corresponding to metering pin values (PINDM), main gear
STROKN	Array of strut stroke values corresponding to metering pin values (PINDN), nose gear
SXM	Number of main gear struts
SXN	Number of nose gear struts
TAILAC	Acceleration at tail station
TAILRM	Distance from tail station to CG
TAKOFF	Rotation velocity of aircraft

SYMBOL DEFINITION THRUST Total thrust of aircraft TIME Array of simulation times at which CG acceleration time history points are stored TIMEX Counter variable for printed output TIME Array of simulation times at which pilot station time history are stored TSM Tire spring constant, main gear TSN Tire spring constant, nose gear **TYPRUN** Defines simulation as takeoff or taxi VOM Main gear strut fully extended volume VON Nose gear strut fully extended volume Weight of aircraft WM Main gear unsprung weight WN Nose gear unsprung weight X Simulation time **XLONG** Length of time axis for Calcomp plot XLONG2 XLONG/2 **XPROF** Location for printing of "NOSE GEAR TRACK" on Calcomp plot **XSTOP** XLONG+5 YP Array containing runway segment elevation points and slope from end of previous segment, rear main gear YPR Array containing runway segment elevation points and slope from end of previous segment, rear main gear (Class E simulation only) YPN Array containing runway segment elevation points and slope from end of previous segment, nose gear ZRDOT

(Class E simulation only)

Slope of runway segment at end point, rear main gear

SYMBOL.	DEFINITION
ZNDOT	Slope of runway segment at end point, nose gear
TAYLOR	
AOM	Net orifice area main and form
	Net orifice area, main gear (OAM-metering pin area)
AON	Net orifice area, nose gear (OAN-metering pin area)
*BSN	Nose landing gear minimum bearing separations
#BSM	Main landing gear minimum bearing separations
COM	Damping coefficient, main gear
CON	Damping coefficient, nose gear
DRAGA	Aerodynamic drag
DRAGT	Rolling Drag
*FFON	Nose landing gear seal friction
*FFOM	Main landing gear seal friction
*FLN	Nose landing gear lower friction force
*FLM	Main landing gear lower friction force
FSM	Total force in all main gear struts
FSN	Total force in all nose gear struts
FSTN	Net force on secondary piston, nose gear (Class E simulation only)
FST1	Net force on secondary piston, rear main gear (Class E simulation only)
FST2	Net force on secondary piston, front main gear (Class E simulation only)
FTH	Force in tires, main gear
FTN	Force in tires, nose gear
*FUN	Nose landing gear upper friction force
*FUM	Main landing gear upper friction force
*Class B simul	ation with Strut Friction only

SYMBOL	DEFINITION
*OFFN	Nose landing gear axle offset
#OFFM	Main landing gear axle offset
*PHIN	Nose landing gear angle from the vertical
#PHIM	Main landing gear angle from the vertical
≑PLN	Nose landing gear piston length
*PLM	Main landing gear piston length
QTDM	Total velocity due to flexible modes at main gear
QTDN	Total velocity due to flexible modes at nose gear
QTM	Total deflection due to flexible modes at main gear
QTN	Total deflection due to flexible modes at nose gear
SLOPEM	Slope of line drawn through two metering pin points, main gear
SLOPEN	Slope of line drawn through two metering pin points, nose gear
SSM	Pneumatic force, main gear
SSN	Pneumatic force, nose gear
T(2)	CG vertical displacement
T(4)	Unsprung mass vertical displacement, front main gear
T(6)	Unsprung mass vertical displacement, nose gear
T(8)	Rigid body pitch angle of aircraft
T(10)	Horizontal distance of aircraft
T(12)	Unsprung mass vertical displacement, rear main gear (Class E simulation only)
TD(2)	Time derivative of T(2)
TD(4)	Time derivative of T(4)
TD(6)	Time derivative of T(6)
TD(8)	Time derivative of T(8)
*Class B simul	ation with Strut Friction only

SYMBOL	DEFINITION
TD(10)	Time derivative of T(19)
TD(12)	Time derivative of T(12) (Class E simulation only)
TDD(2)	Time derivative of TD(2)
TDD (4)	Time derivative of TD(4)
TDD(6)	Time derivative of TD(6)
TDD (8)	Time derivative of $TD(3)$
TDD (10)	Time derivative of TD(10)
TDD(12)	Time derivative of TD(12) (Class E simulation only)
VELM	Total strut velocity, main gear
VELN	Total strut velocity, nose gear
VLIFT	Aerodynamic lift force
XMAIN	Strut stroke, main gear
XMLK	Absolute value of XMAIN
XNLK	Absolute value of XNOSE
XNOSE	Strut stroke, main gear
YCEPN	Y intercept of line drawn through two metering pin points, nose gear
Z	Distance of aircraft from beginning of a 4 ft runway segment
ZPM	Runway elevation, rear main gear
ZPMR	Runway elevation, front main gear (Class E simulation only)
ZPN	Runway elevation, nose gear
<u>IC</u>	
RM	Static reaction force at main gear
RMIT	Static reaction force at rear main gear (Class E simulation only)
RM2T	Static reaction force at front main gear (Class E simulation only)

SYMBOL	DEFINITION
RN	Static reaction force at nose gear
RSM	RM - WM
RSN	RN - WN
THETAI	Rigid body initial pitch angle
XRMAIN	Test variable for rigid body initial conditions (Class E simulation only)
ZCGI	Initial CG vertical displacement
ZMI	Initial tire deflection, main gear
ZNI	Initial tire deflection, nose gear
COEFF	
A	Coefficient of polynomial fit to runway profile segment
В	Coefficient of polynomial fit to runway profile segment
С	Coefficient of polynomial fit to runway profile segment
D	Coefficient of polynomial fit to runway profile segment
Y	Runway profile elevation value
TL00K	
I	Index variable
N	Number of values in metering pin - stroke table
Р	Metering pin diameter or net orifice area for aircraft with metering tubes or flutted metering pins
S	Strut stroke in metering pin table
SLOPE	Slope of line drawn between two metering pin points
YCEPT	Y intercept of line drawn between two metering pin points

APPENDIX E

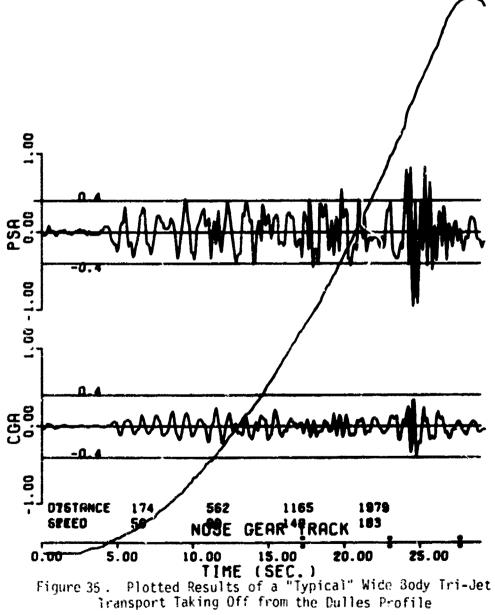
TYPICAL WIDE BODIED TRI-JET TRANSPORT DATA AND SIMULATIONS

This appendix contains data obtained late in the study which represents a "TYPICAL" Wide Bodied Tri-Jet Transport and may be used to simulate Class C and D aircraft of this type. This appendix also contains takeoff simulations over the Will Rogers and Dulles Profiles.



HIDE-BODY TRI-JET COMPOSITE. 391500

WILL ROGERS INT AIRPORT



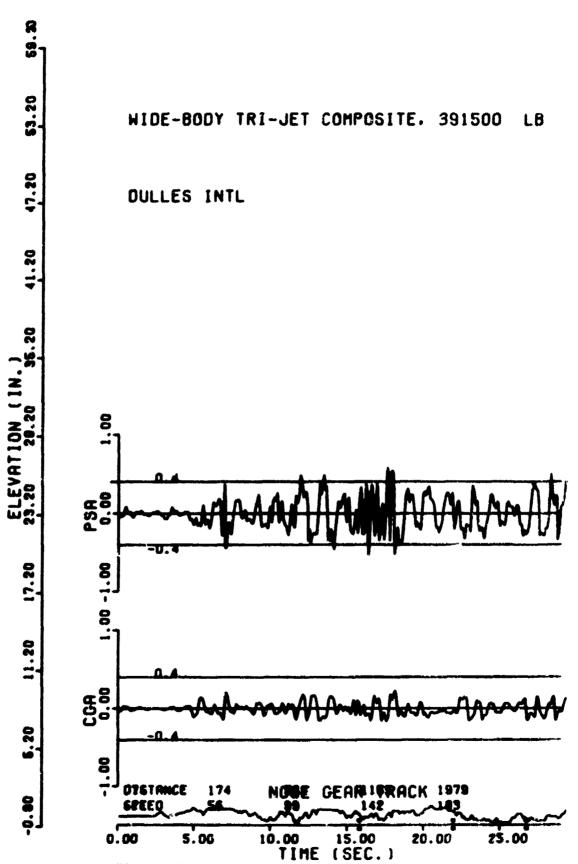


Figure 36. Plotted Results of a "Typical" Wide Body Tr--Jet Transport Taking Off from the Dulles Profile

TABLE XVII. List of Data Used to Simulate the Wide-Body Tri-Jet Composite

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č.				A25A= 3533.03	
7	# **	± } C t c	=NC bd	AREA	
301166	.,	66.48	25.43	.079	
, C				•	1:3
Ŧ E	# ** (A	# T	# *	::	PIN DIAMETER
6.5	17 6 01	S	33.60	() ()	
331500.0		130.03		•	3120K = N03E
11	# **	2 A M	# K T	, ,	TROKE
					10

PIN DIAMETER

STABLE MAIN

6.003 1.203 1.203

Continued
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XVI I
TABLE

SET. HASS	20002	2690.0	2000.0	2000.3	2002	2.000.0	2000.0	2000	2.000.0	2000	20002	2002	2000.0	2008.0	2000.0
OMEGA	7.63	12.93	15.18	10.19	22.37	25.19	27.34	29.17	35.95	39.26	39.96	47.73	52.27	61.98	71.36
SITAIL	93	13	:A	=	61	. 53	:	~	1.39	-1.25	•	#ñ iñ	13	1.53	-1.24
NIMIS	23		•	1.25	13	03	÷	.19	?	1.51	£1.	•	1.52	-1.83	-1-35
SECTS	50	60.	23	-1.01	47	*	35	14.	. 31	#. •••			27	-1.22	*6.
STNOSE	25	59	1.58	1.13	.17	3	.10	62	.53	15	.ts	• 0 •	•	ž.	61.
S e 15	17	:	2.52	2.15	.53	-1.54	. 33	-1.26	1.93	72	1.67	2.75	.6	-3.15	•
433	-	~	m	.•	10			•	•	3	#	2	:	:	: 3

-24.787 #441M= -22.219 #405E= -15.139 READTM= -31137. READTM= -160363. * IE 3Z T4ETAI* -.010282 -1.557 = 11.7 -3.276

2HI=

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